

Rank Bounds for Design Matrices and Applications

Abdul Basit
University of Notre Dame

Institut Henri Poincaré
Model Theory and Combinatorics
January 31st, 2018

Ordinary lines

- Let \mathcal{P} be a set of n points in \mathbb{R}^2 .
- For $r \geq 2$, define a r -rich line to be a line containing exactly r points.
- Let $t_r = t_r(\mathcal{P})$ denote the number of r -rich lines determined by \mathcal{P} .
- **General Question:** What can be said about t_r ?

Ordinary lines

- Let \mathcal{P} be a set of n points in \mathbb{R}^2 .
- For $r \geq 2$, define a r -rich line to be a line containing exactly r points.
- Let $t_r = t_r(\mathcal{P})$ denote the number of r -rich lines determined by \mathcal{P} .
- **General Question:** What can be said about t_r ?
- For this talk, we focus on t_2 .
- A 2-rich line is referred to as an **ordinary line**.

The Sylvester-Gallai theorem

Sylvester-Gallai theorem: Let $\mathcal{P} \subset \mathbb{R}^2$ be a finite set of points such that every line has at least 3 points, i.e., $t_2 = 0$. Then points of \mathcal{P} are collinear.

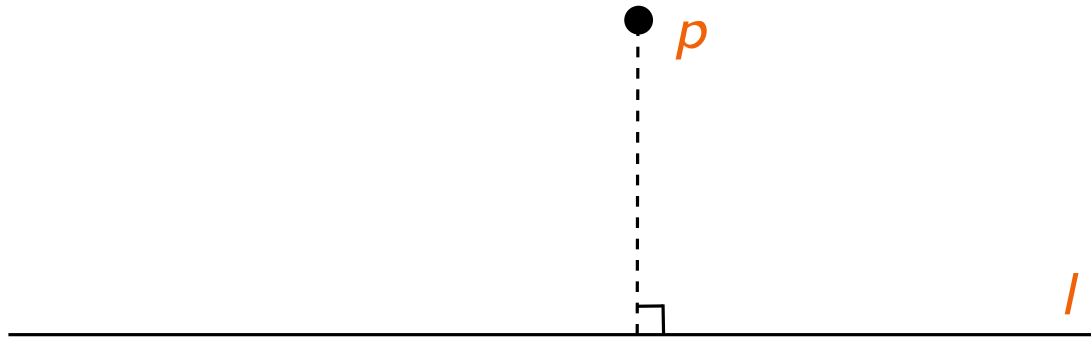
The Sylvester-Gallai theorem

Sylvester-Gallai theorem: Let $\mathcal{P} \subset \mathbb{R}^2$ be a finite set of points such that every line has at least 3 points, i.e., $t_2 = 0$. Then points of \mathcal{P} are collinear.

- Proposed by Sylvester (1893) and then by Erdős (1943).
- Proofs by Melchior (1940), Gallai (1944), Kelly (1948) and many others.

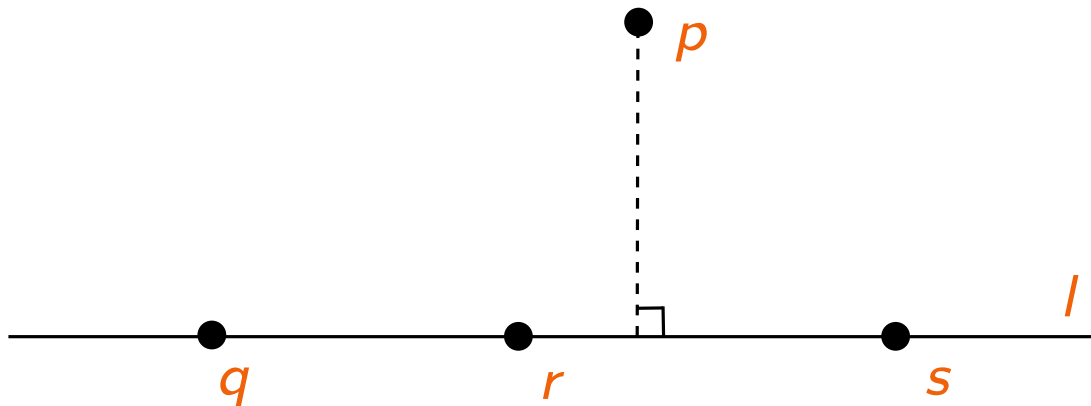
Kelly's proof

Assume for contradiction that there exists a point set \mathcal{P} , not all collinear, with no ordinary lines. Let (p, l) be a point-line pair, with $p \in \mathcal{P}$ and l meeting at least 2 points of \mathcal{P} , with smallest non-zero distance.



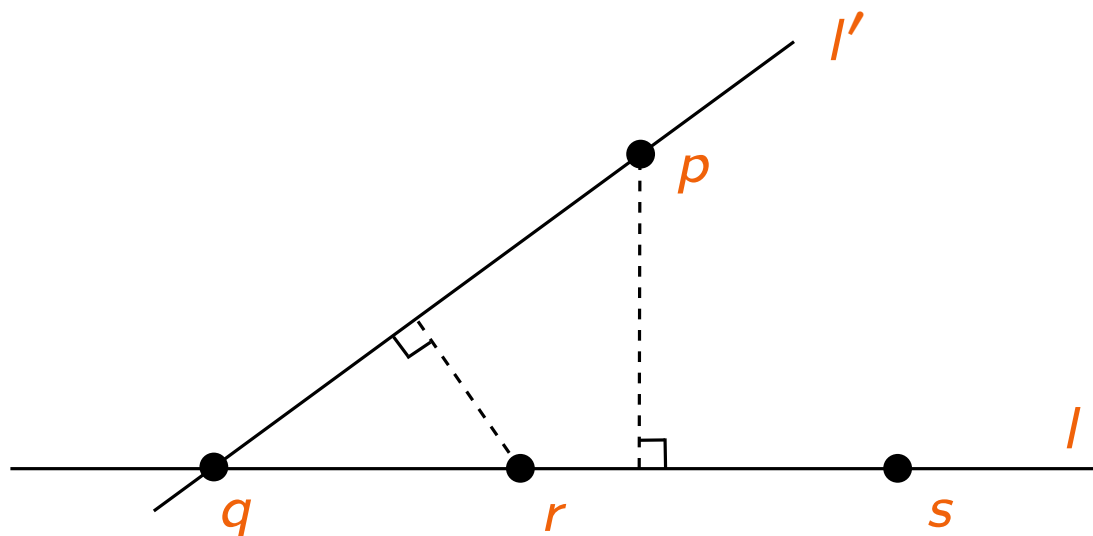
Kelly's proof

Assume for contradiction that there exists a point set \mathcal{P} , not all collinear, with no ordinary lines. Let (p, l) be a point-line pair, with $p \in \mathcal{P}$ and l meeting at least 2 points of \mathcal{P} , with smallest non-zero distance.



Kelly's proof

Assume for contradiction that there exists a point set \mathcal{P} , not all collinear, with no ordinary lines. Let (p, l) be a point-line pair, with $p \in \mathcal{P}$ and l meeting at least 2 points of \mathcal{P} , with smallest non-zero distance.



But now (r, l') is another point-line pair with smaller distance. Contradiction!

The number of ordinary lines

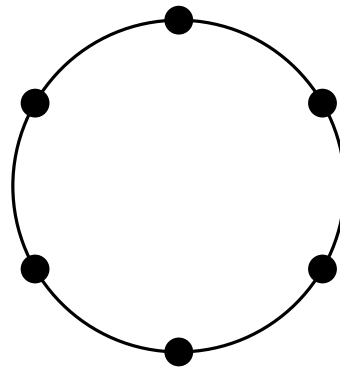
For n non-collinear points, how small can t_2 be?

The number of ordinary lines

For n non-collinear points, how small can t_2 be?

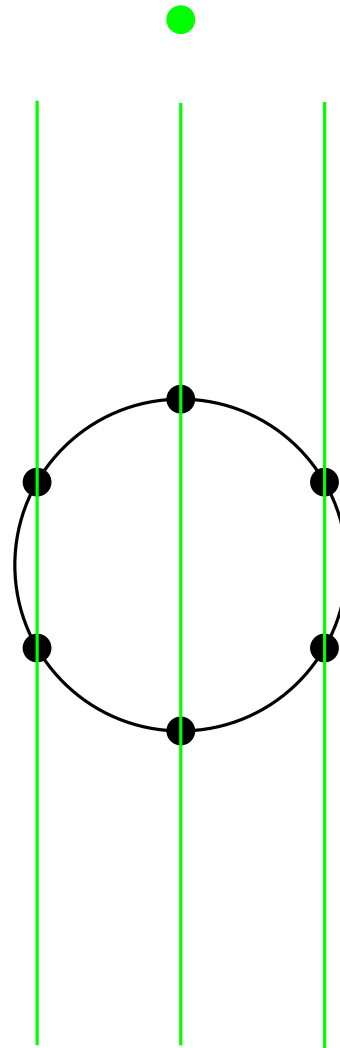
- If exactly $n - 1$ points are collinear, then $t_2 = n - 1$.
- If exactly $n - k$ points are collinear, then $t_2 \geq k(n - 2k)$.
Works if $1 \leq k < n/2$.

Böröczky construction



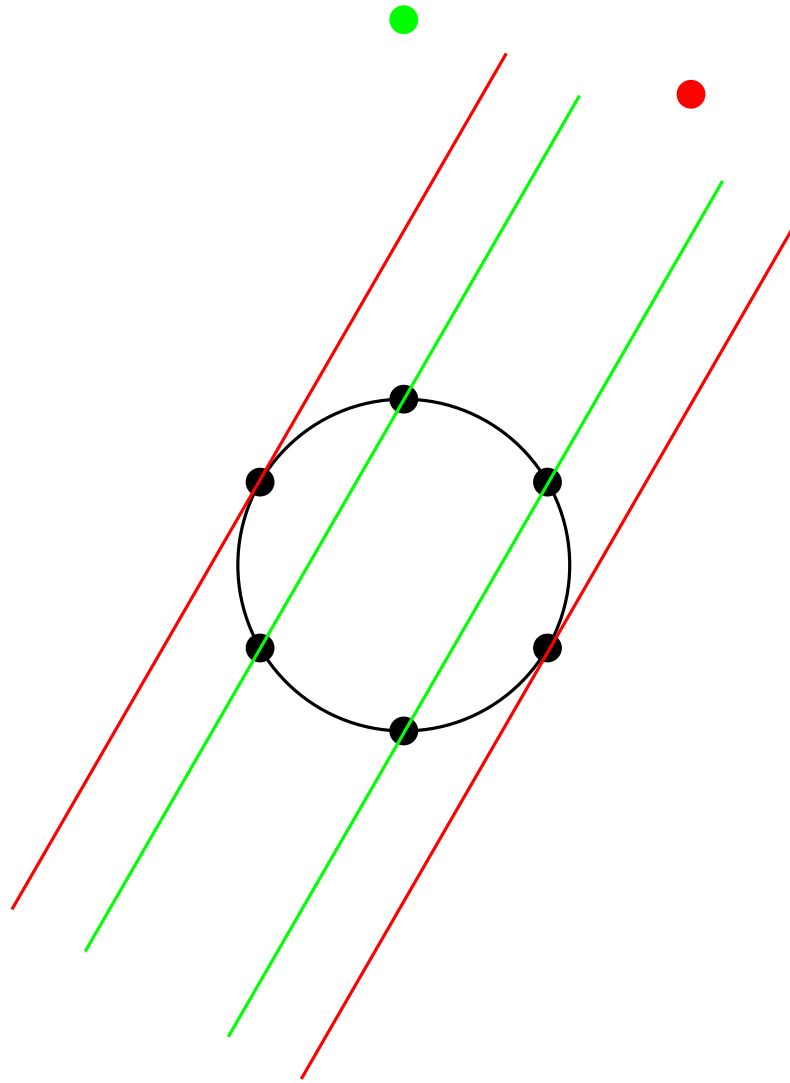
$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



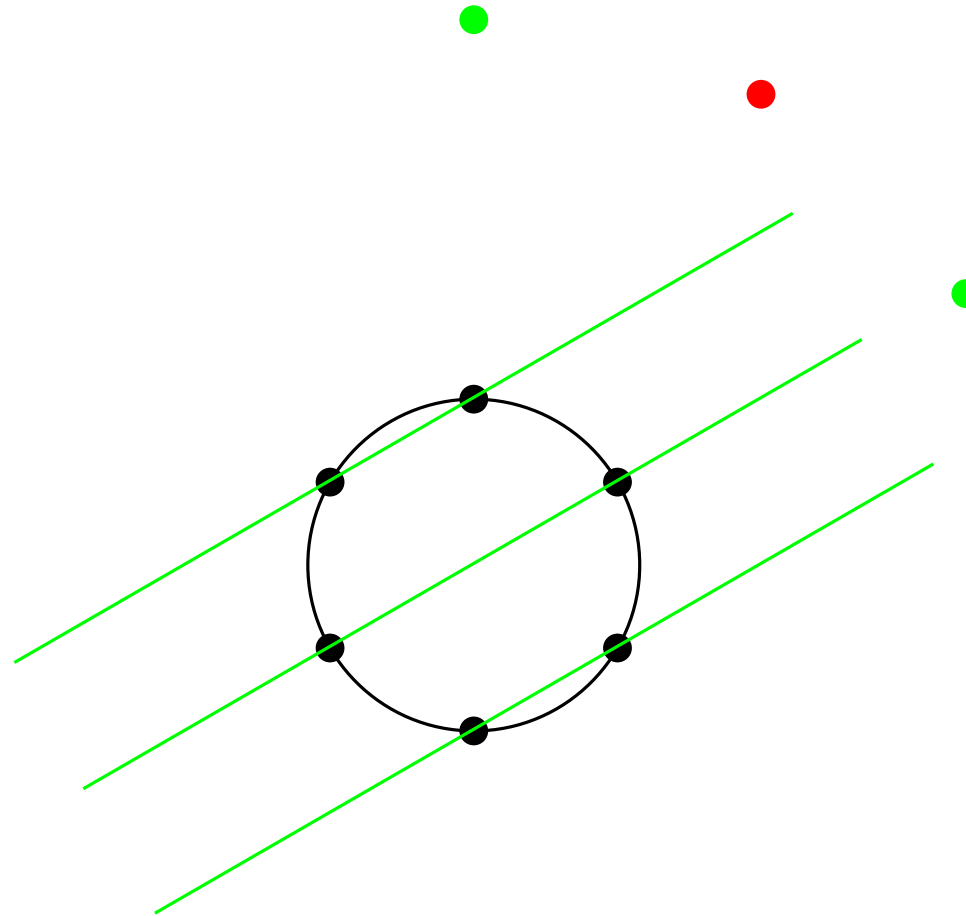
$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



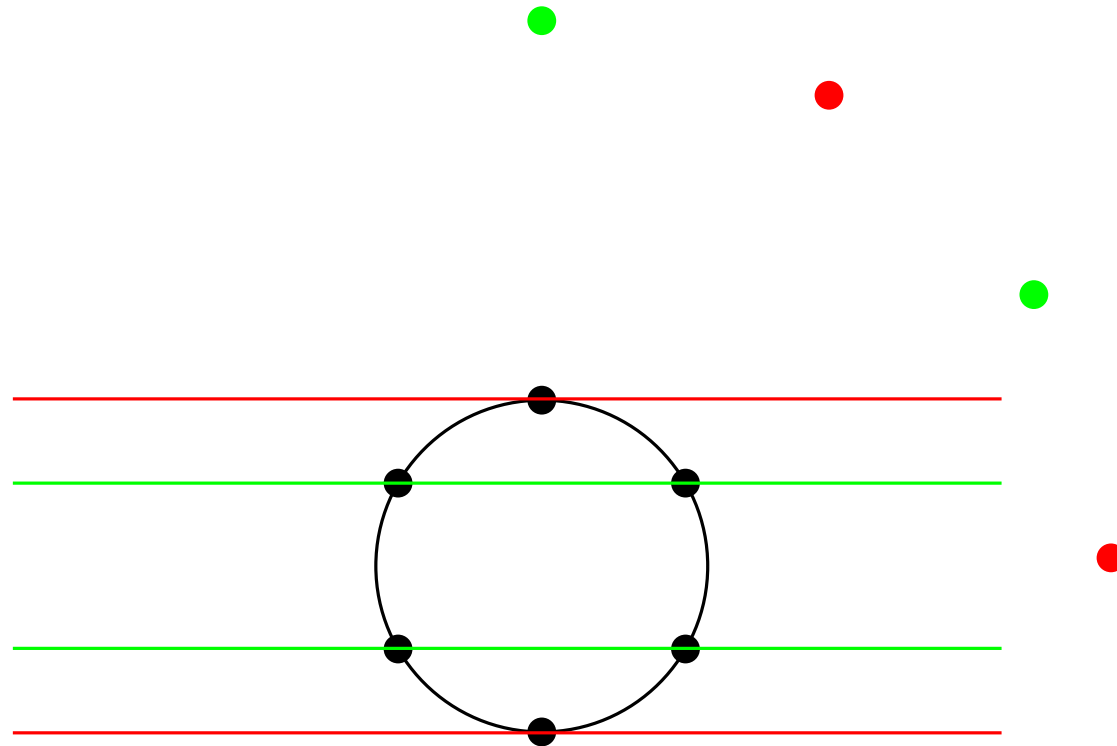
$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



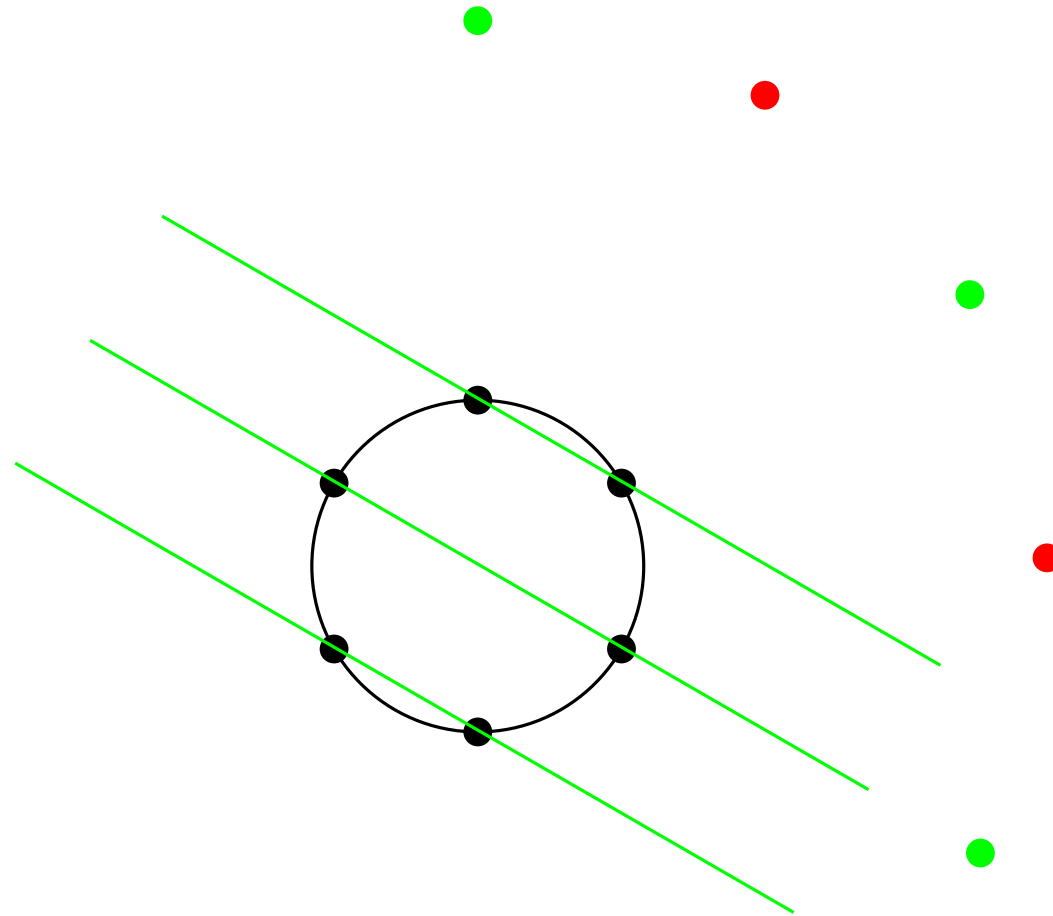
$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



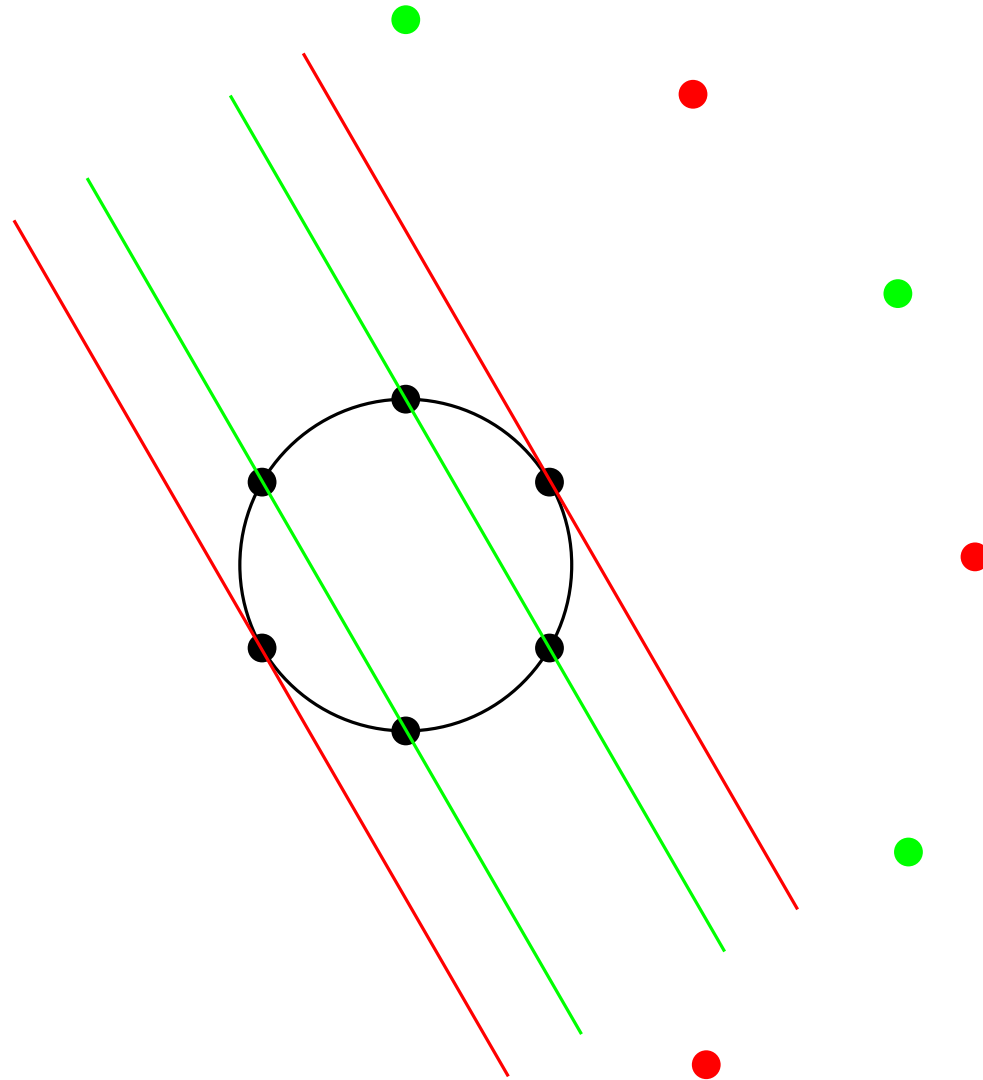
$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



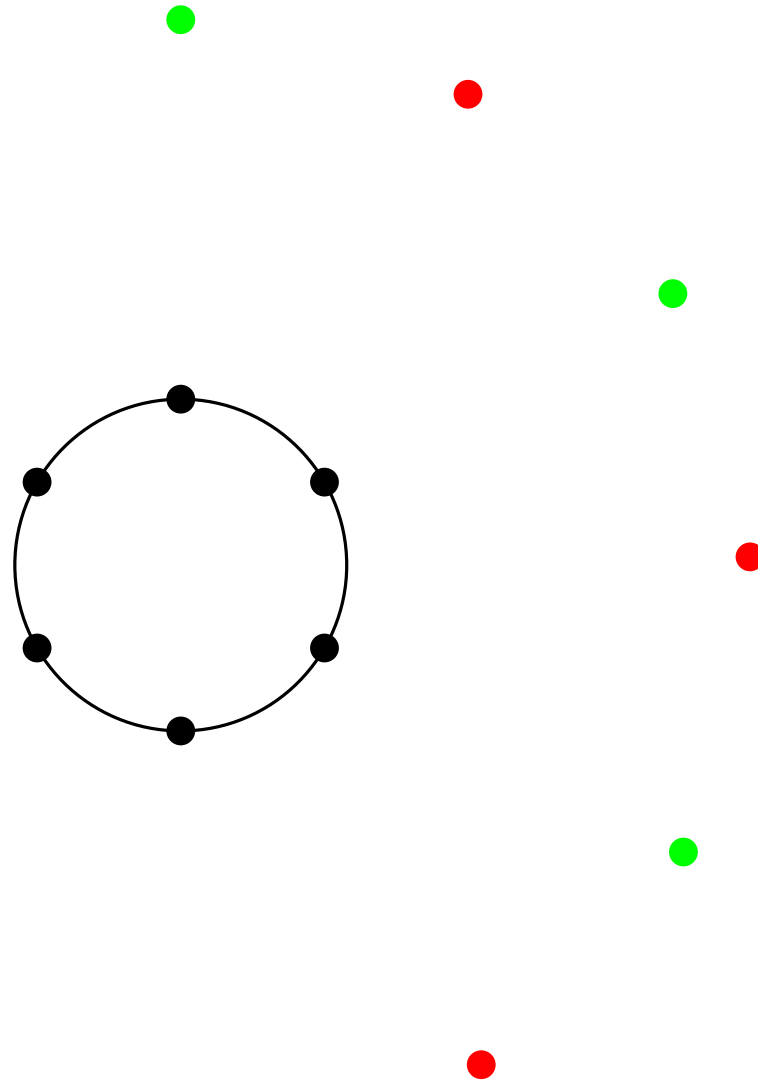
$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



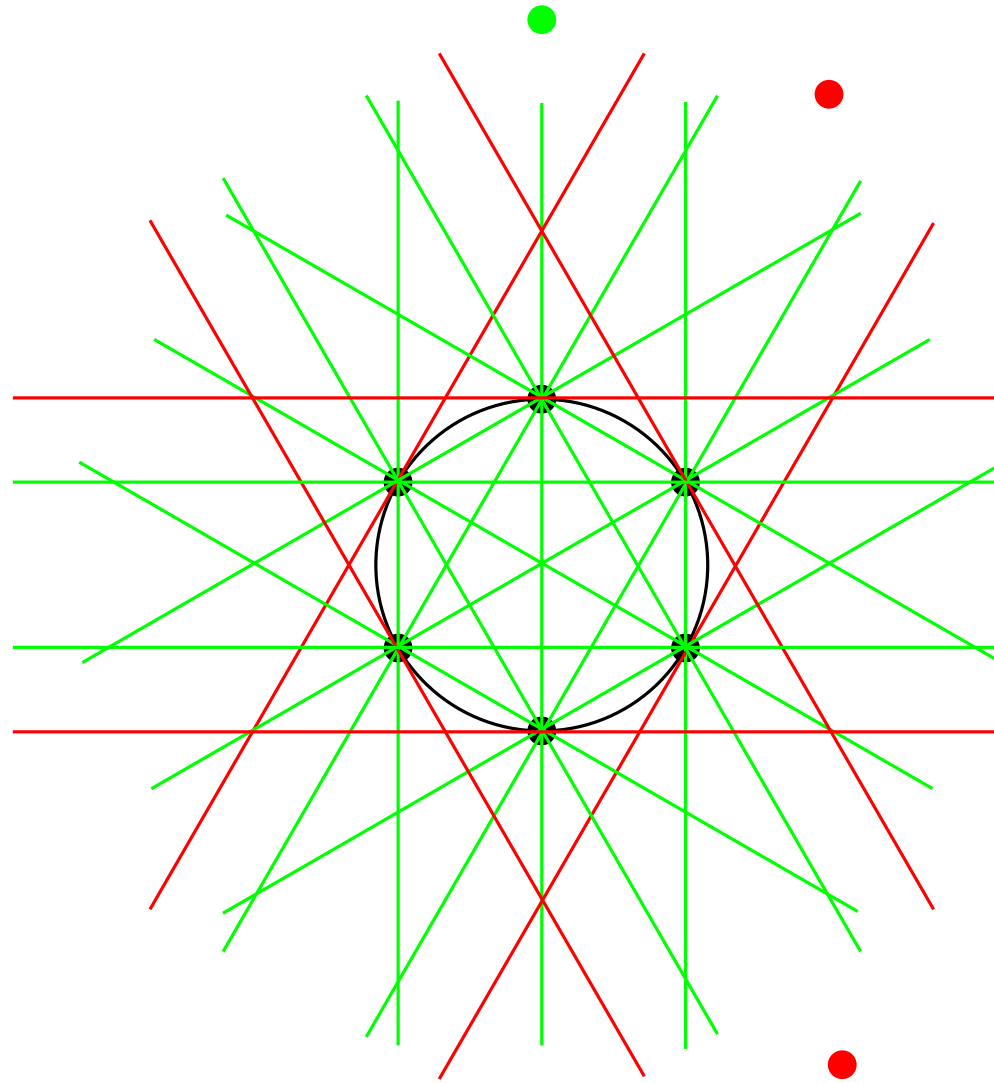
$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



$n = 12$ points determining $n/2 = 6$ ordinary lines

Böröczky construction



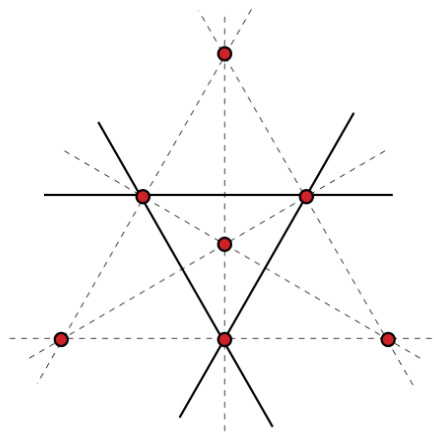
$n = 12$ points determining $n/2 = 6$ ordinary lines

Dirac-Motzkin conjecture

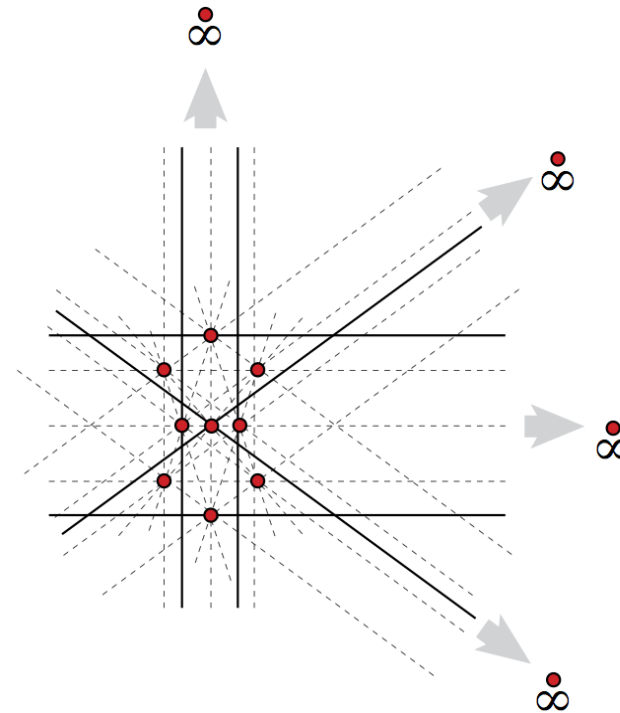
Dirac-Motzkin conjecture: If $n > 13$ and \mathcal{P} is a set of n points in \mathbb{R}^2 , not all collinear, then $t_2 \geq n/2$.

Dirac-Motzkin conjecture

Dirac-Motzkin conjecture: If $n > 13$ and \mathcal{P} is a set of n points in \mathbb{R}^2 , not all collinear, then $t_2 \geq n/2$.



$n = 7, t_2 = 3$



$n = 13, t_2 = 6$

*Images from Wikipedia

Dirac-Motzkin conjecture

Dirac-Motzkin conjecture: If $n > 13$ and \mathcal{P} is a set of n points in \mathbb{R}^2 , not all collinear, then $t_2 \geq n/2$.

- Melchior (1940): $t_2 \geq 3$.
- Motzkin (1951): $t_2 = \Omega(\sqrt{n})$.
- Kelly-Moser (1958): $t_2 \geq 3n/7$.
- Csima-Sawyer (1993): $t_2 \geq 6n/13$.

Dirac-Motzkin conjecture

Dirac-Motzkin conjecture: If $n > 13$ and \mathcal{P} is a set of n points in \mathbb{R}^2 , not all collinear, then $t_2 \geq n/2$.

- Melchior (1940): $t_2 \geq 3$.
- Motzkin (1951): $t_2 = \Omega(\sqrt{n})$.
- Kelly-Moser (1958): $t_2 \geq 3n/7$.
- Csimma-Sawyer (1993): $t_2 \geq 6n/13$.

Green-Tao (2013): There exists a constant n_0 such that if $n > n_0$ and \mathcal{P} is a set of n points in \mathbb{R}^2 , not all collinear, then $t_2 \geq n/2$.

Algebraic Structure: If $t_2 < Kn$ (K constant) then all but $O(K)$ points lie on a cubic curve.

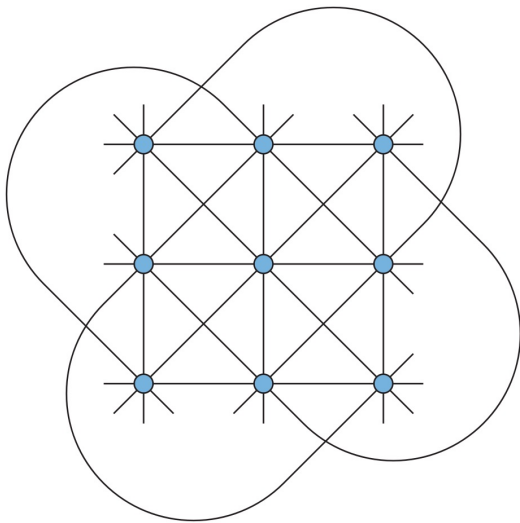
A counter-example in \mathbb{C}^2

The Sylvester-Gallai theorem depends crucially on properties of \mathbb{R} .
Fails for other fields such as for \mathbb{C} .

A counter-example in \mathbb{C}^2

The Sylvester-Gallai theorem depends crucially on properties of \mathbb{R} .
Fails for other fields such as for \mathbb{C} .

The Hesse Configuration: Nine points and twelve 3-rich lines.



- Realized by the inflection points of the homogenous cubic $X^3 + Y^3 + Z^3 = 0$.
- In homogenous coordinates
 $[\omega, 0, 1], [\omega^2, 0, 1], [-1, 0, 1]$
 $[0, \omega, 1], [0, \omega^2, 1], [0, -1, 1]$
 $[-\omega, 1, 0], [-\omega^2, 1, 0], [1, 1, 0]$
where ω is a third root of -1 .

Ordinary lines in \mathbb{C}^3

- Kelly (1986): Let $\mathcal{P} \subset \mathbb{C}^3$ be a finite set of points not contained in a plane, then there must exist an ordinary line, i.e., $t_2 \geq 1$.

Ordinary lines in \mathbb{C}^3

- Kelly (1986): Let $\mathcal{P} \subset \mathbb{C}^3$ be a finite set of points not contained in a plane, then there must exist an ordinary line, i.e., $t_2 \geq 1$.
- B.-Dvir-Saraf-Wolf (2016): Let $\mathcal{P} \subset \mathbb{C}^d$, $d \geq 3$, be a set of n points.
 1. If the points are not coplanar then $t_2 = \Omega(n)$.
 2. If $o(n)$ points are contained in any three-dimensional subspace, then $t_2 = \Omega(n^2)$

More Generalizations

[Ai, Barak, de Zeeuw, Dvir, Elliott, Kelly, Moser, Motzkin, Saraf, Schicho, Swanepoel, Valculescu, Wigderson, Wolf, Yehudayoff, . . .]

More Generalizations

[Ai, Barak, de Zeeuw, Dvir, Elliott, Kelly, Moser, Motzkin, Saraf, Schicho, Swanepoel, Valculescu, Wigderson, Wolf, Yehudayoff, ...]

- **Quantative Sylvester-Gallai:** If for every point, there are δn other points such that the line containing the two points contains a third. Then $\dim(\mathcal{P}) = O\left(\frac{1}{\delta}\right)$.

More Generalizations

[Ai, Barak, de Zeeuw, Dvir, Elliott, Kelly, Moser, Motzkin, Saraf, Schicho, Swanepoel, Valculescu, Wigderson, Wolf, Yehudayoff, ...]

- **Quantative Sylvester-Gallai:** If for every point, there are δn other points such that the line containing the two points contains a third. Then $\dim(\mathcal{P}) = O\left(\frac{1}{\delta}\right)$.
- **Stable Sylvester-Gallai:** If the distance between any two points is bounded by B and for every pair of points, there is a third point ϵ -collinear to the pair. Then $\dim_{\epsilon}(\mathcal{P}) = O(B)$.

More Generalizations

[Ai, Barak, de Zeeuw, Dvir, Elliott, Kelly, Moser, Motzkin, Saraf, Schicho, Swanepoel, Valculescu, Wigderson, Wolf, Yehudayoff, ...]

- **Quantative Sylvester-Gallai:** If for every point, there are δn other points such that the line containing the two points contains a third. Then $\dim(\mathcal{P}) = O\left(\frac{1}{\delta}\right)$.
- **Stable Sylvester-Gallai:** If the distance between any two points is bounded by B and for every pair of points, there is a third point ϵ -collinear to the pair. Then $\dim_{\epsilon}(\mathcal{P}) = O(B)$.
- **Other objects:** Ordinary circles, conics, planes, ...

Incidences to Rank Bounds

Several recent results use the “Method of Design Matrices”

Incidences to Rank Bounds

Several recent results use the “Method of Design Matrices”

- Let V be the matrix whose i^{th} row is the i^{th} point p_i .

Incidences to Rank Bounds

Several recent results use the “Method of Design Matrices”

- Let V be the matrix whose i^{th} row is the i^{th} point p_i .
- If p_i, p_j, p_k are collinear, then $\exists a_i, a_j, a_k$ such that $a_i p_i + a_j p_j + a_k p_k = 0$.
- Construct a matrix A whose rows corresponds to collinear triples.

$$\begin{bmatrix}
 a_1 & a_2 & a_3 & 0 & \dots & \dots & 0 \\
 0 & \dots & 0 & a_j & 0 & \dots & 0 & a_k \\
 \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot
 \end{bmatrix}
 \begin{bmatrix}
 \dots & p_1 & \dots \\
 \dots & p_2 & \dots \\
 \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot \\
 & & V
 \end{bmatrix}
 = \underline{0}$$

Incidences to Rank Bounds

Several recent results use the “Method of Design Matrices”

- Let V be the matrix whose i^{th} row is the i^{th} point p_i .
- If p_i, p_j, p_k are collinear, then $\exists a_i, a_j, a_k$ such that $a_i p_i + a_j p_j + a_k p_k = 0$.
- Construct a matrix A whose rows corresponds to collinear triples.

$$\begin{bmatrix}
 a_1 & a_2 & a_3 & 0 & \dots & \dots & 0 \\
 0 & \dots & 0 & a_j & 0 & \dots & 0 & a_k \\
 \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot
 \end{bmatrix}
 \begin{bmatrix}
 \dots & p_1 & \dots \\
 \dots & p_2 & \dots \\
 \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot \\
 & V &
 \end{bmatrix}
 = \underline{0}$$

- Upper bound $\text{rank}(V)$ by lower bounding $\text{rank}(A)$.
- Select a subset of collinear triples \rightarrow make sure A is a design matrix.

Design matrices

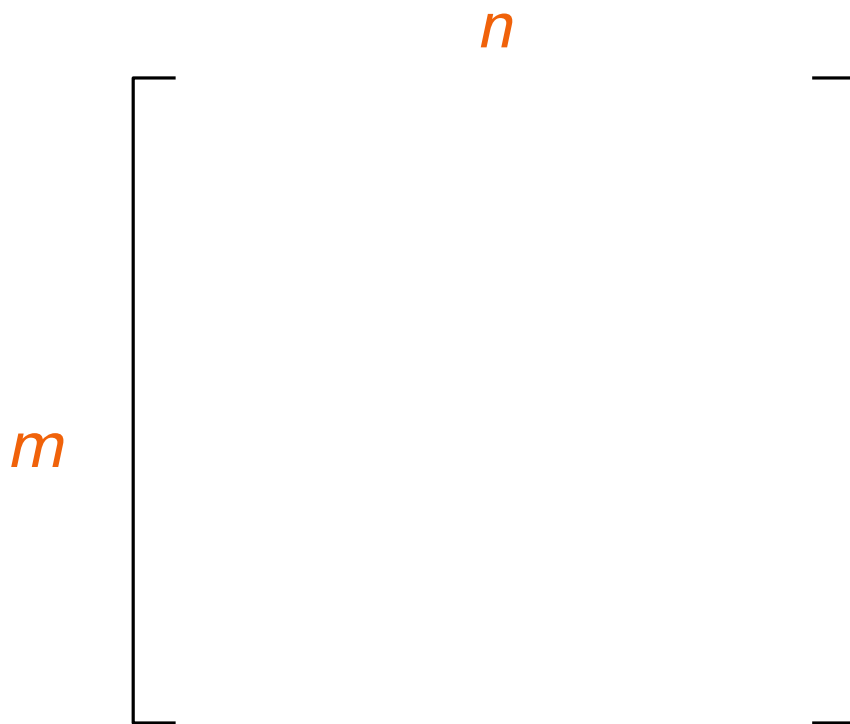
A $m \times n$ matrix A is referred to as a (q, k, t) -design matrix if

1. Every row has support of size at most q .
2. Every column has support of size at least k .
3. The support of any two columns intersect in at most t entries.

Design matrices

A $m \times n$ matrix A is referred to as a (q, k, t) -design matrix if

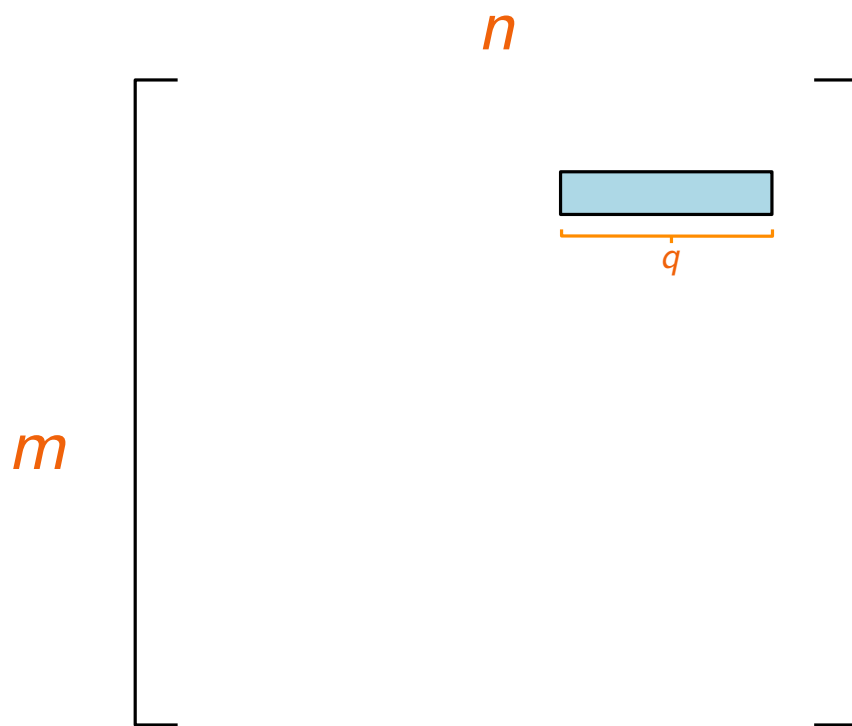
1. Every row has support of size at most q .
2. Every column has support of size at least k .
3. The support of any two columns intersect in at most t entries.



Design matrices

A $m \times n$ matrix A is referred to as a (q, k, t) -design matrix if

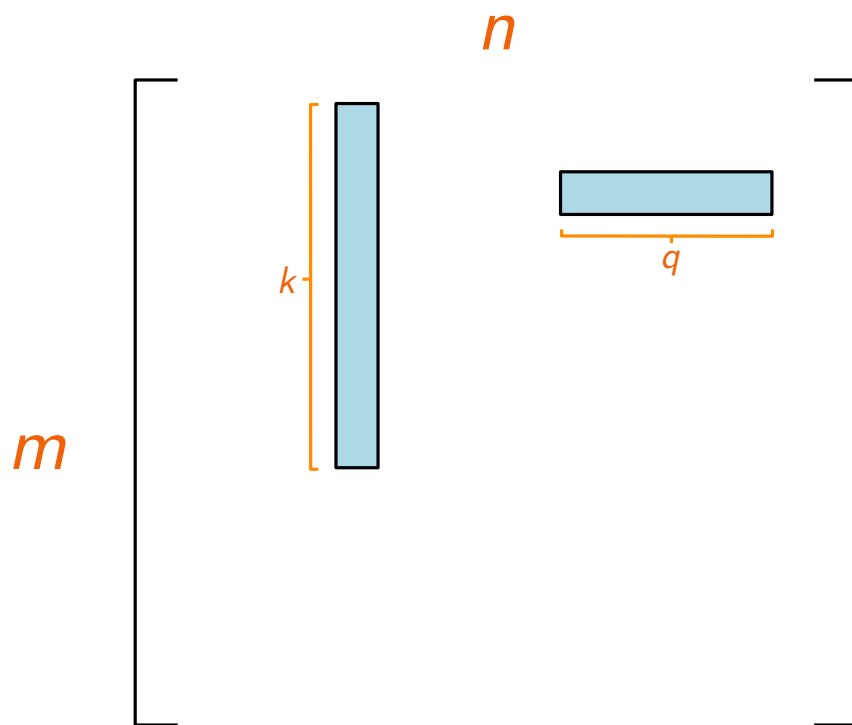
1. Every row has support of size at most q .
2. Every column has support of size at least k .
3. The support of any two columns intersect in at most t entries.



Design matrices

A $m \times n$ matrix A is referred to as a (q, k, t) -design matrix if

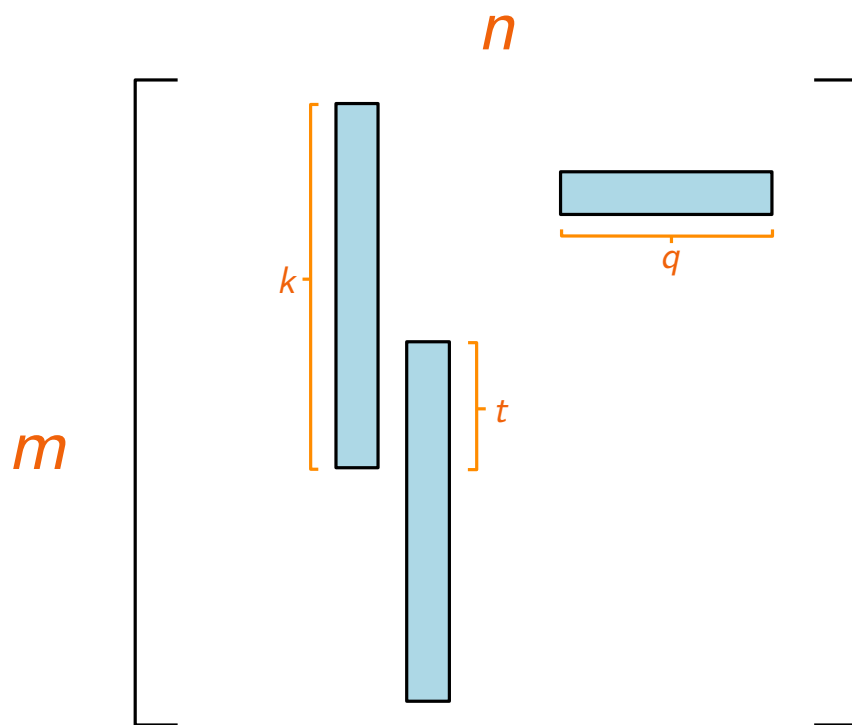
1. Every row has support of size at most q .
2. Every column has support of size at least k .
3. The support of any two columns intersect in at most t entries.



Design matrices

A $m \times n$ matrix A is referred to as a (q, k, t) -design matrix if

1. Every row has support of size at most q .
2. Every column has support of size at least k .
3. The support of any two columns intersect in at most t entries.



Design matrices

BDWY '11, DSW '12: If A is an $m \times n$ complex (q, k, t) -design matrix, then $\text{rank}(A) \geq n - \frac{ntq^2}{k}$.

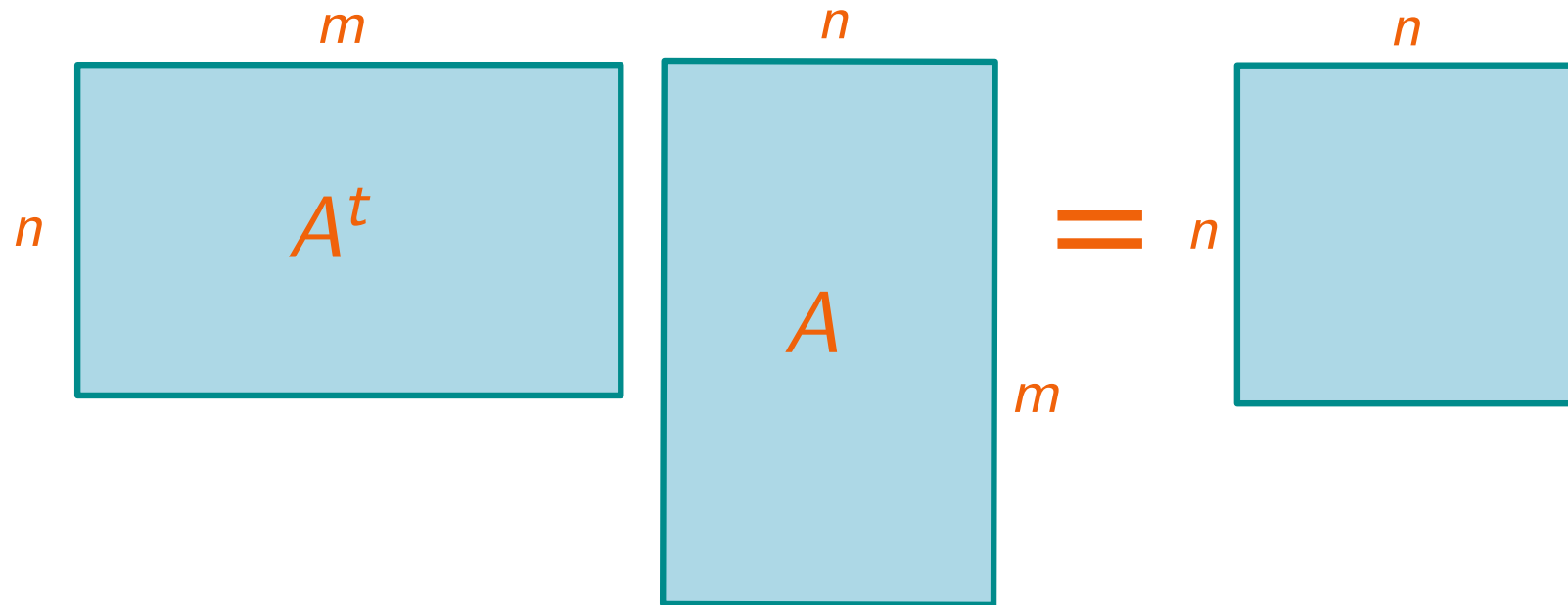
Design matrices

BDWY '11, DSW '12: If A is an $m \times n$ complex (q, k, t) -design matrix, then $\text{rank}(A) \geq n - \frac{ntq^2}{k}$.

Usual setting: q, t constant, k linear $\Rightarrow \text{rank}(A) \geq n - O(1)$.

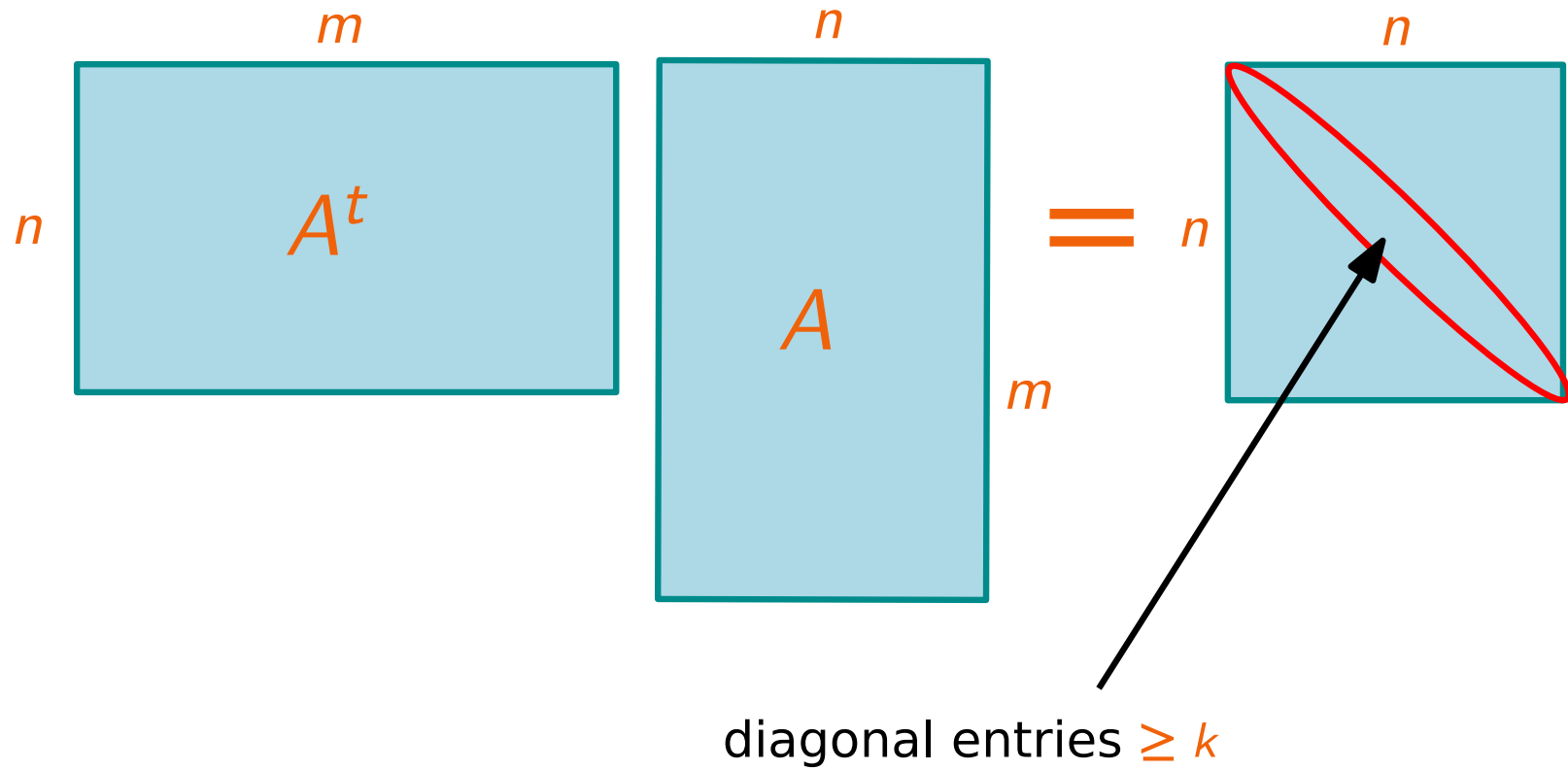
Proof Idea

Easy Case: A is a 0/1 matrix.



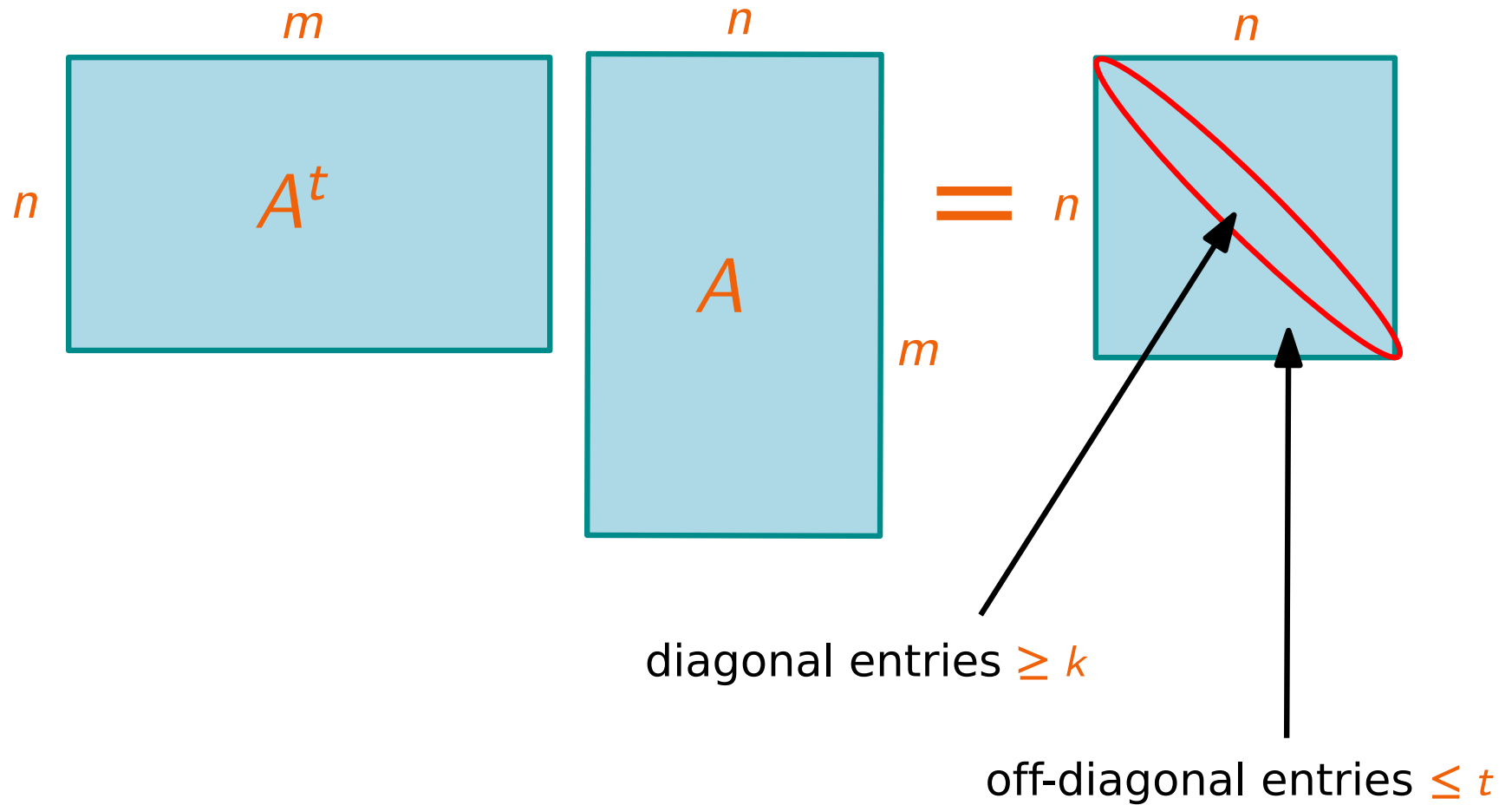
Proof Idea

Easy Case: A is a 0/1 matrix.



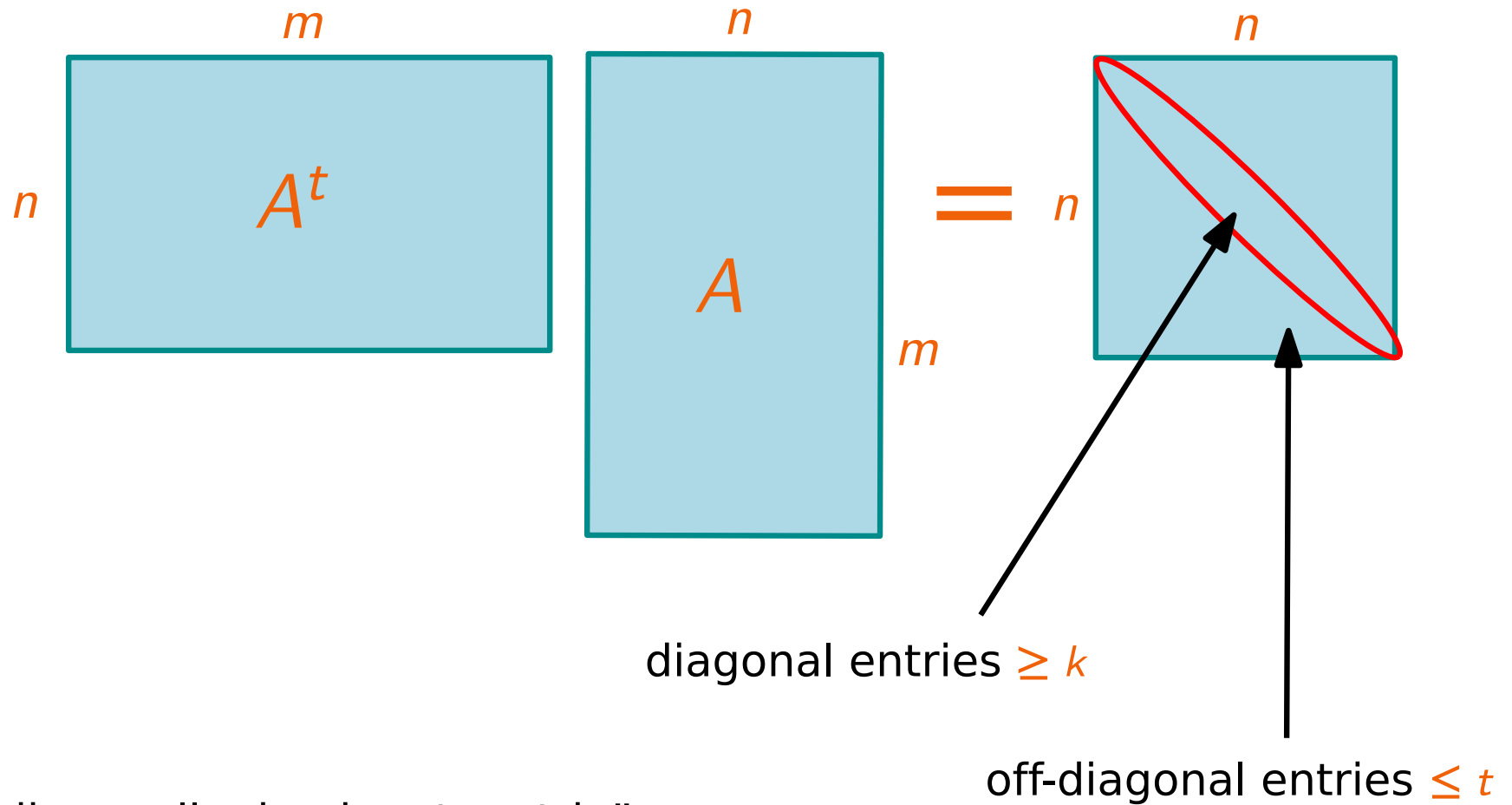
Proof Idea

Easy Case: A is a 0/1 matrix.



Proof Idea

Easy Case: A is a 0/1 matrix.



“diagonally dominant matrix”

Proof Idea

Lemma (folklore): If M $n \times n$ Hermitian matrix with $M_{ii} \geq L$, then

$$\text{rank}(M) \geq \frac{n^2 L^2}{nL^2 + \sum_{i \neq j} M_{ij}^2}.$$

Proof Idea

Lemma (folklore): If M $n \times n$ Hermitian matrix with $M_{ii} \geq L$, then

$$\text{rank}(M) \geq \frac{n^2 L^2}{nL^2 + \sum_{i \neq j} M_{ij}^2}.$$

Proof Sketch:

$$n^2 L^2 = \text{tr}(M)^2 = \left(\sum_{i=1}^n \lambda_i \right)^2 \leq n \sum_{i=1}^n \lambda_i^2 = n \sum_{i,j} |M_{ij}|^2.$$

Proof Idea

General Case: Reduce to easy case using **matrix scaling**.

Find (if exists?) R, C of full rank such that RAC has *balanced* coefficients.

Proof Idea

General Case: Reduce to easy case using [matrix scaling](#).

Find (if exists?) R, C of full rank such that RAC has *balanced* coefficients.

That is: 1. $\forall j \in [n], \sum_{i \in [m]} A_{ij} = \frac{m}{n}$ (column sums = m/n)

2. $\forall i \in [m], \sum_{j \in [n]} A_{ij} = 1$ (row sums = 1)

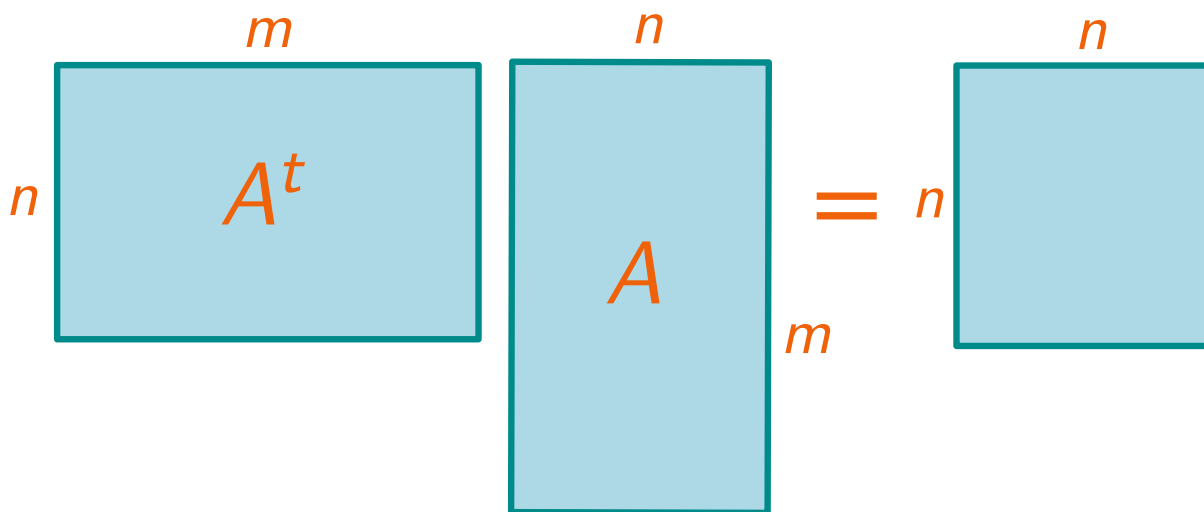
Proof Idea

General Case: Reduce to easy case using [matrix scaling](#).

Find (if exists?) R, C of full rank such that RAC has *balanced* coefficients.

That is: 1. $\forall j \in [n], \sum_{i \in [m]} A_{ij} = \frac{m}{n}$ (column sums = m/n)

2. $\forall i \in [m], \sum_{j \in [n]} A_{ij} = 1$ (row sums = 1)



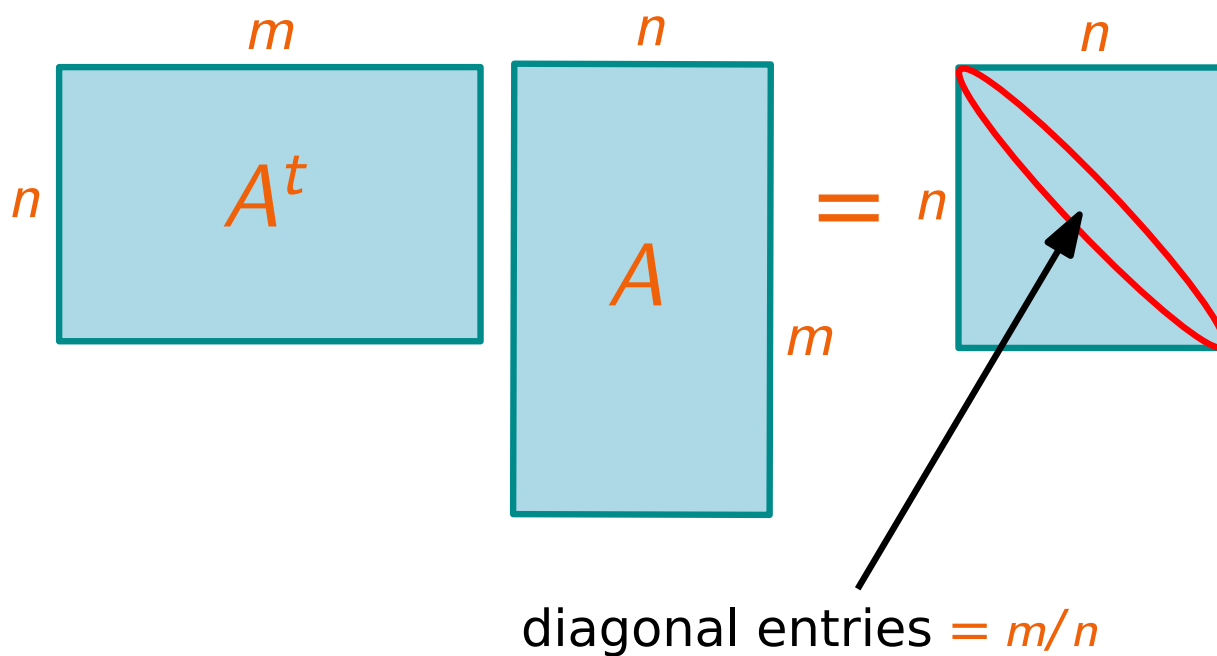
Proof Idea

General Case: Reduce to easy case using **matrix scaling**.

Find (if exists?) R, C of full rank such that RAC has *balanced* coefficients.

That is: 1. $\forall j \in [n], \sum_{i \in [m]} A_{ij} = \frac{m}{n}$ (column sums = m/n)

2. $\forall i \in [m], \sum_{j \in [n]} A_{ij} = 1$ (row sums = 1)



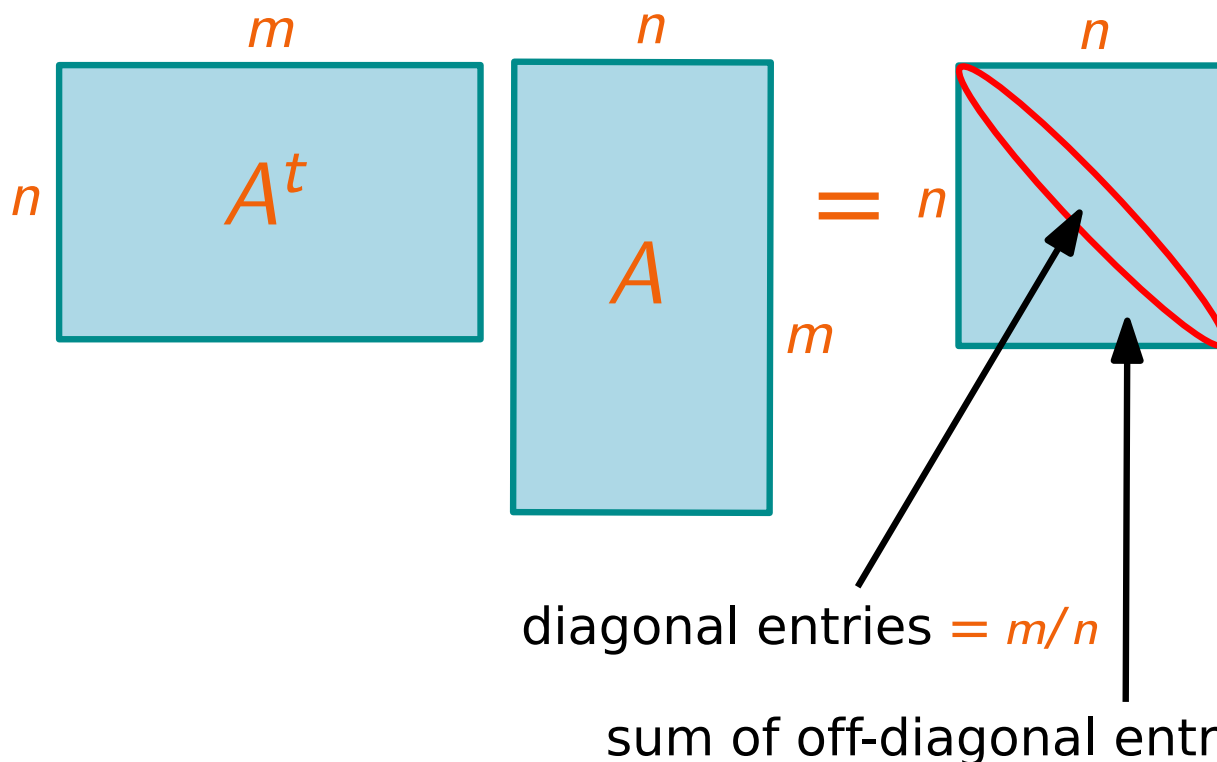
Proof Idea

General Case: Reduce to easy case using **matrix scaling**.

Find (if exists?) R, C of full rank such that RAC has *balanced* coefficients.

That is: 1. $\forall j \in [n], \sum_{i \in [m]} A_{ij} = \frac{m}{n}$ (column sums = m/n)

2. $\forall i \in [m], \sum_{j \in [n]} A_{ij} = 1$ (row sums = 1)

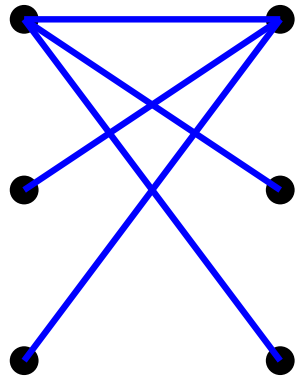


Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)



G

1	1	1
1	0	0
1	0	0

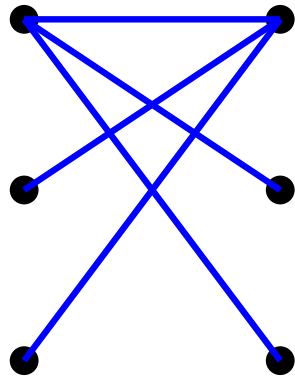
$A(G)$

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Find (if exists?) R, C full rank such that RAC has row sums
and column sums ≈ 1 .

Allowed to multiply rows and columns by scalars.



G

1	1	1
1	0	0
1	0	0

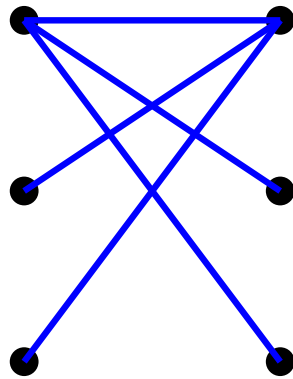
$A(G)$

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Find (if exists?) R, C full rank such that RAC has row sums
and column sums ≈ 1 .

Allowed to multiply rows and columns by scalars.



G

$1/3$	$1/3$	$1/3$
1	0	0
1	0	0

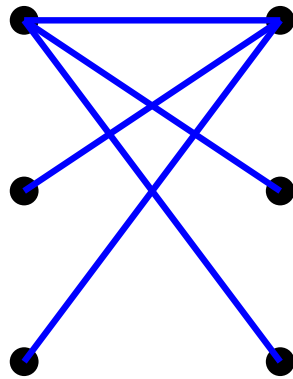
$A(G)$

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Find (if exists?) R, C full rank such that RAC has row sums
and column sums ≈ 1 .

Allowed to multiply rows and columns by scalars.



G

$1/7$	1	1
$3/7$	0	0
$3/7$	0	0

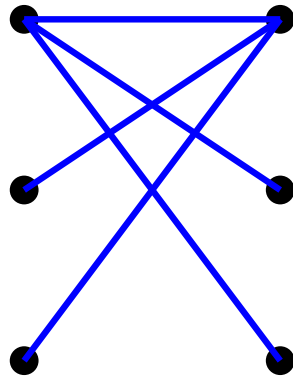
$A(G)$

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Find (if exists?) R, C full rank such that RAC has row sums
and column sums ≈ 1 .

Allowed to multiply rows and columns by scalars.



G

$1/15$	$7/15$	$7/15$
1	0	0
1	0	0

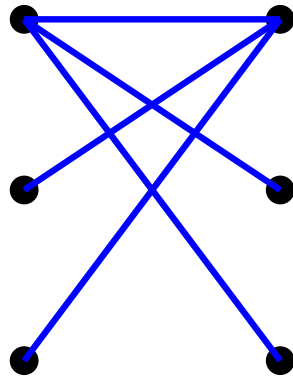
$A(G)$

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Find (if exists?) R, C full rank such that RAC has row sums
and column sums ≈ 1 .

Allowed to multiply rows and columns by scalars.



G

$1/31$	1	1
$15/31$	0	0
$15/31$	0	0

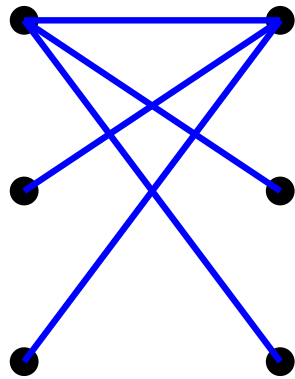
$A(G)$

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Find (if exists?) R, C full rank such that RAC has row sums
and column sums ≈ 1 .

Allowed to multiply rows and columns by scalars.



G

0	1/2	1/2
1	0	0
1	0	0

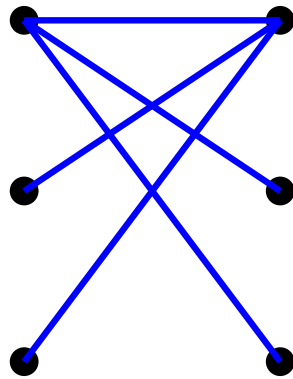
$A(G)$

Matrix Scaling Algorithm

A non-negative real matrix. Try making it doubly stochastic.
(e.g., the adjacency matrix $A = A(G)$ of a bipartite graph G .)

Find (if exists?) R, C full rank such that RAC has row sums
and column sums ≈ 1 .

Allowed to multiply rows and columns by scalars.



G

0	1	1
1/2	0	0
1/2	0	0

$A(G)$

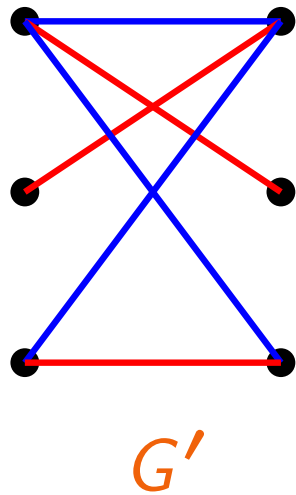
Doesn't converge!

Matrix Scaling Algorithm

Matrix Scaling Theorem [Sinkhorn]: The scaling algorithm converges if A has no $a \times b$ zero minor with $a + b > n \iff G$ has a perfect matching.

Matrix Scaling Algorithm

Matrix Scaling Theorem [Sinkhorn]: The scaling algorithm converges if A has no $a \times b$ zero minor with $a + b > n \iff G$ has a perfect matching.

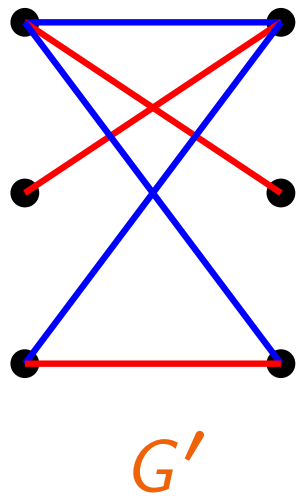


1	1	1
1	1	0
1	0	0

$A(G')$

Matrix Scaling Algorithm

Matrix Scaling Theorem [Sinkhorn]: The scaling algorithm converges if A has no $a \times b$ zero minor with $a + b > n \iff G$ has a perfect matching.

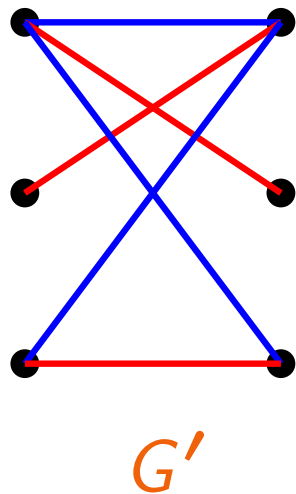


1/3	1/3	1/3
1/2	1/2	0
1	0	0

$A(G')$

Matrix Scaling Algorithm

Matrix Scaling Theorem [Sinkhorn]: The scaling algorithm converges if A has no $a \times b$ zero minor with $a + b > n \iff G$ has a perfect matching.

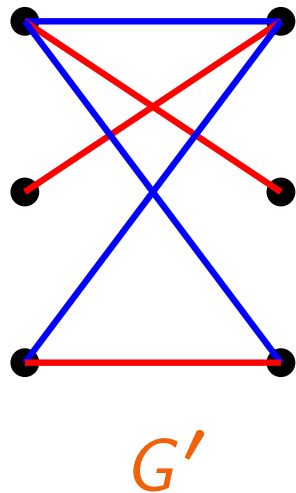


$2/11$	$2/5$	1
$3/11$	$3/5$	0
$6/11$	0	0

$A(G')$

Matrix Scaling Algorithm

Matrix Scaling Theorem [Sinkhorn]: The scaling algorithm converges if A has no $a \times b$ zero minor with $a + b > n \iff G$ has a perfect matching.

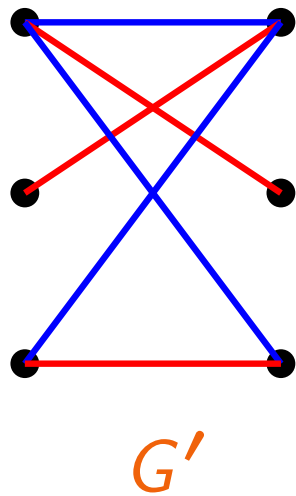


$10/87$	$22/87$	$57/87$
$15/48$	$33/48$	0
1	0	0

$A(G')$

Matrix Scaling Algorithm

Matrix Scaling Theorem [Sinkhorn]: The scaling algorithm converges if A has no $a \times b$ zero minor with $a + b > n \iff G$ has a perfect matching.



0	0	1
0	1	0
1	0	0

$A(G')$

Thank you.